IDISASTER ROBOTICS

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<u>Disaster Robotics Intelligent Robotics And Autonomous</u> <u>Agents Series</u>

Angelo Cangelosi, Matthew Schlesinger

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regulating the real time interaction of its body brain and environment can autonomously acquire an increasingly complex set of sensorimotor and mental capabilities This volume drawing on insights from psychology computer science linguistics neuroscience and robotics offers the first comprehensive overview of a rapidly growing field After providing some essential background information on robotics and developmental psychology the book looks in detail at how developmental robotics models and experiments have attempted to realize a range of behavioral and cognitive capabilities. The examples in these chapters were chosen because of their direct correspondence with specific issues in child psychology research each chapter begins with a concise and accessible overview of relevant empirical and theoretical findings in developmental psychology The chapters cover intrinsic motivation and curiosity motor development examining both manipulation and locomotion perceptual development including face recognition and perception of space social learning emphasizing such phenomena as joint attention and cooperation language from phonetic babbling to syntactic processing and abstract knowledge including models of number learning and reasoning strategies Boxed text offers technical and methodological details for both psychology and robotics experiments Learning for Adaptive and Reactive Robot Control Aude Billard, Sina Mirrazavi, Nadia Figueroa, 2022-02-01 Methods by which robots can learn control laws that enable real time reactivity using dynamical systems with applications and exercises This book presents a wealth of machine learning techniques to make the control of robots more flexible and safe when interacting with humans It introduces a set of control laws that enable reactivity using dynamical systems a widely used method for solving motion planning problems in robotics These control approaches can replan in milliseconds to adapt to new environmental constraints and offer safe and compliant control of forces in contact The techniques offer theoretical advantages including convergence to a goal non penetration of obstacles and passivity The coverage of learning begins with low level control parameters and progresses to higher level competencies composed of combinations of skills Learning for Adaptive and Reactive Robot Control is designed for graduate level courses in robotics with chapters that proceed from fundamentals to more advanced content Techniques covered include learning from demonstration optimization and reinforcement learning and using dynamical systems in learning control laws trajectory planning and methods for compliant and force control Features for teaching in each chapter applications which range from arm manipulators to whole body control of humanoid robots pencil and paper and programming exercises lecture videos slides and MATLAB code examples available on the author's website an eTextbook platform website offering protected material EPS2 for instructors including solutions Introduction to AI Robotics Robin Murphy, 2000 This text provides the material needed to understand the principles behind the AI approach to robotics and to programme an artificially intelligent robot for applications involving sensing navigation planning and uncertainty Experimental Robotics, 2001 RoboCup ... ,2004 Intelligent Robotics and Autonomous Agents Ronald C. Arkin, 2001, **IROS** Proceedings of the 2004 International Symposium on Collaborative Technologies and Systems, CTS 2004, 2003 *Proceedings of the 2004 IEEE*

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